

Speech Enhancement and Diarization

Introduction to Human Language Technology

Matthew Maciejewski

October 31, 2023

or, towards:

The Cocktail Party Problem¹

¹E.C. Cherry, *Some Experiments on the Recognition of Speech, with One and with Two Ears*. The Journal of the Acoustical Society, 1953

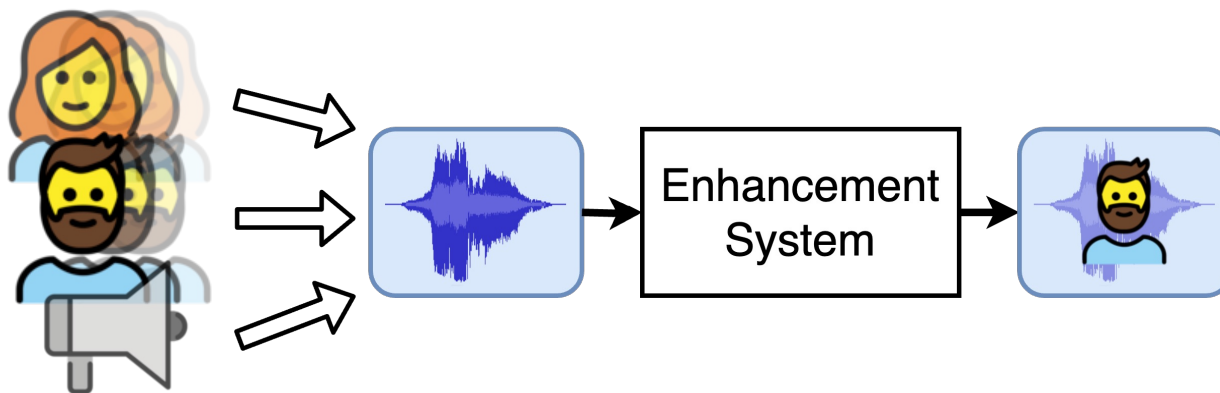
Speech Enhancement (and Separation)

What is speech enhancement?

- Recordings of speech often have a lot of degradation and interfering sounds



- Speech enhancement is the task of removing interferences or reconstructing the clean speech



Why do we care?

- Human listening can always be the end goal
- Degraded audio often leads to degraded performance of downstream systems
- Robust speech technology often integrates techniques developed in enhancement

Mathematical Formulation

Input: $x(t) = s(t) + n(t)$

Output: $y(t) = \hat{s}(t)$

We can also treat $n(t)$ more precisely:

Reverberation: $x(t) = s(t) * h_{RIR}(t)$


Separation: $x(t) = s_1(t) + s_2(t)$

All together:
$$x(t) = \sum_{c=1}^C [s_c(t) * h_c(t)] + \sum_{k=1}^K n_k(t)$$

Performance Evaluation

- Full Reference

- SI-SDR, SNR, (SDR, SIR, SAR), ...
- PESQ, STOI, POLQA, ...


$$\text{SI-SDR} = 10 \log_{10} \frac{|s|^2}{|s - \beta \hat{s}|^2}$$

for β s.t. $s \perp s - \beta \hat{s}$

- No Reference

- Human listening tests! (MOS)
- ITU P.563, SRMRnorm, ...
- DNSMOS, SQAPP, ...

- Downstream Evaluation

- Impact on downstream speech tasks

Significance of Ground Truth

Issues of ground truth are a **significant** aspect of waveform-level tasks

- Non-full-reference metrics have large downsides and typically require synthetic mixtures
- Neural network training targets typically require targets and also require synthetic mixtures
 - Domain mismatch can be a significant problem
- Practical approaches often avoid trying to directly optimize the output waveform

General Approach

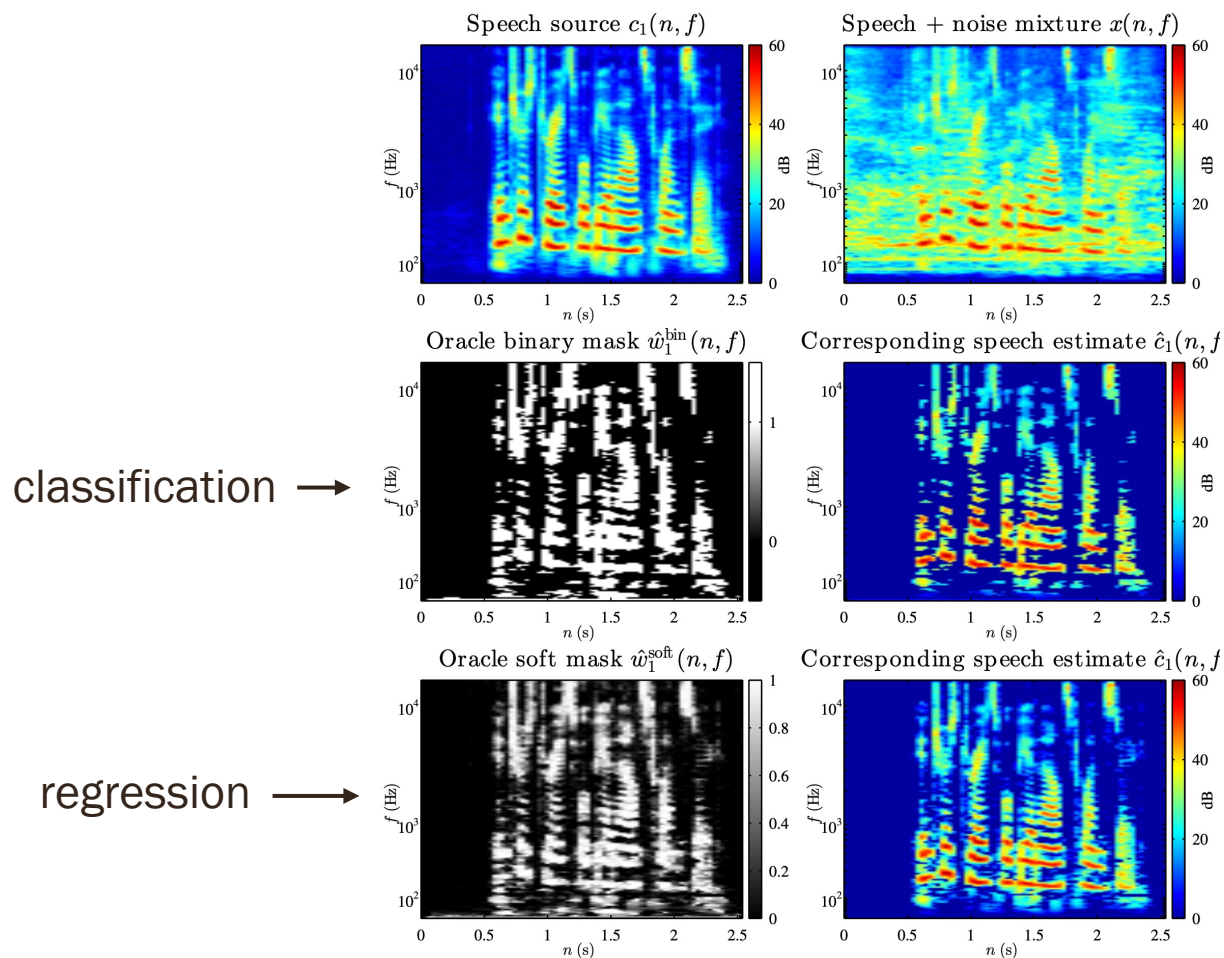
- Speech enhancement methods generally fall under the umbrella of “filtering”, with some further broad categorizations:

temporal filtering vs. spectral filtering

estimation vs. decomposition

- These distinctions are in some sense arbitrary and can often be considered equivalent

Mask-Based Enhancement

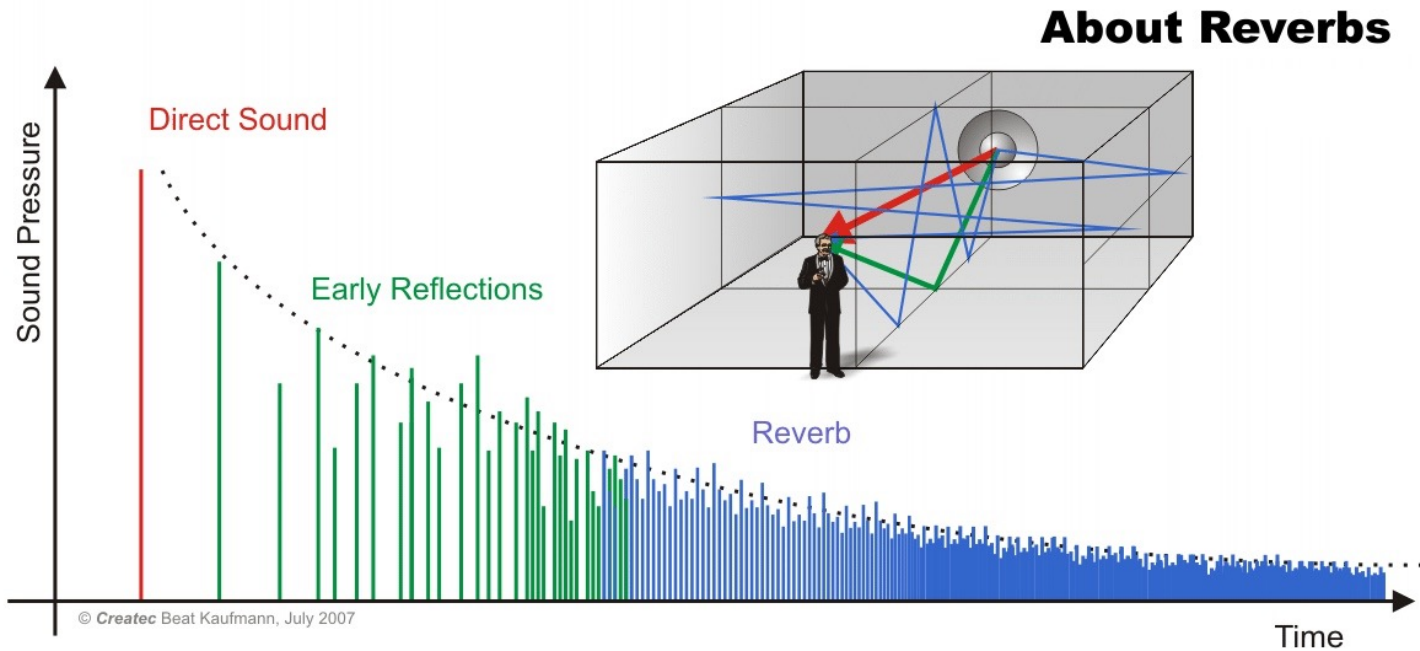


How do we estimate the filters?

- Can be learning-free, unsupervised, supervised
- Estimation of speech presence probability, noise distribution, SNR, power spectra, etc.
- Nonnegative Matrix Factorization (NMF)
 - Decompose magnitude/power spectrum into set of distinct basis spectra
- Independent Component Analysis (ICA)
 - Assumes mixture of mutually-independent stochastic source signals

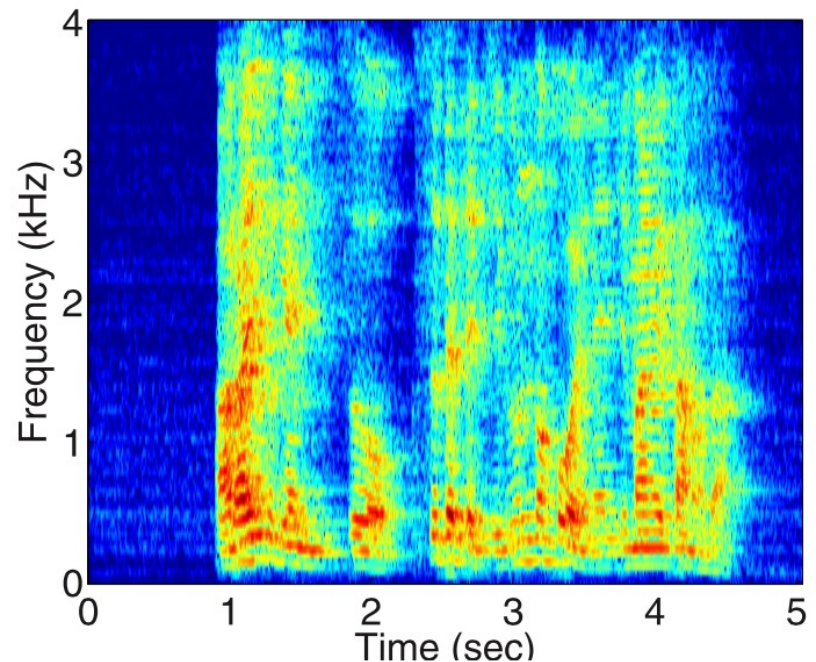
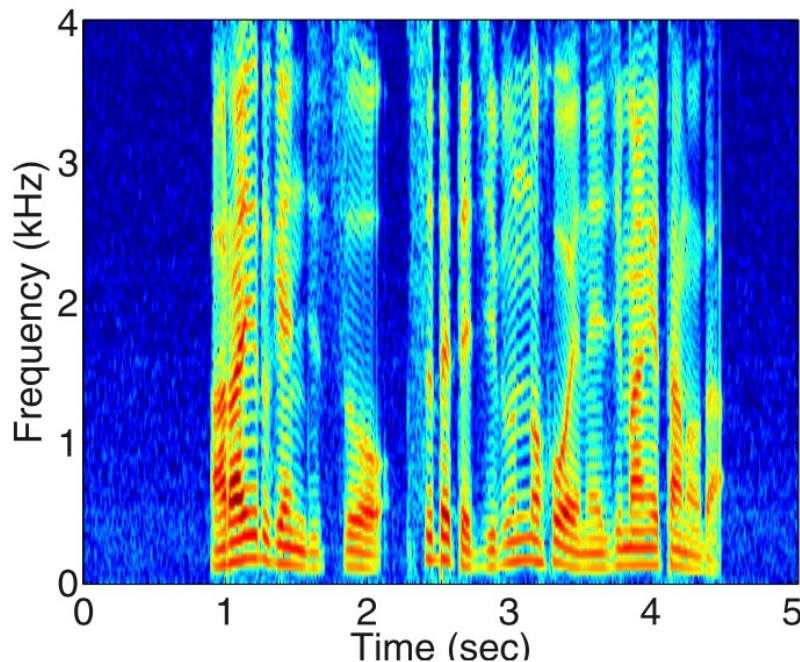
Reverberation

- Room Impulse Response (RIR) captures room reflections and mixes via convolution



Spectral Effect of Reverberation

- Reverb results in spectral smearing



De-Reverberation

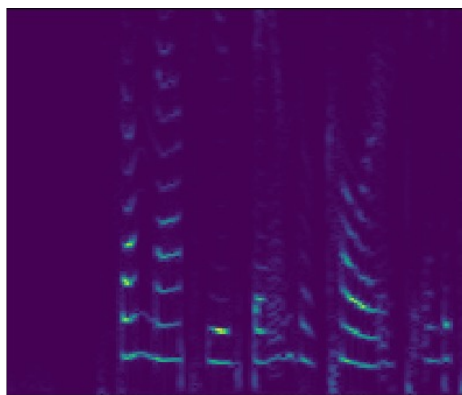
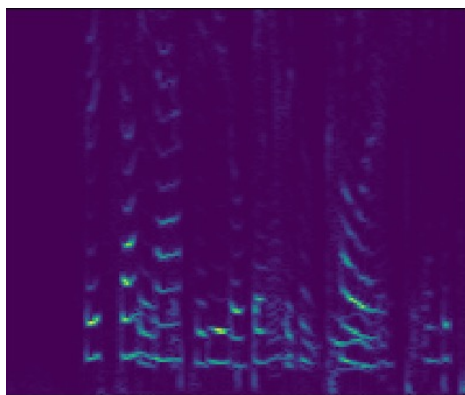
- Most successful practical approach is Weighted Prediction Error (WPE)^{1,2} dereverberation
- The late tail reverberation is estimated and cancelled via delayed linear prediction
 - Iterative procedure to continually update inverse filter
- Avoiding early reflections minimizes corruption of direct path and issue of relative non-stationarity
- “Deep” extension via neural speech Power Spectral Density (PSD) estimation³

Speech Separation

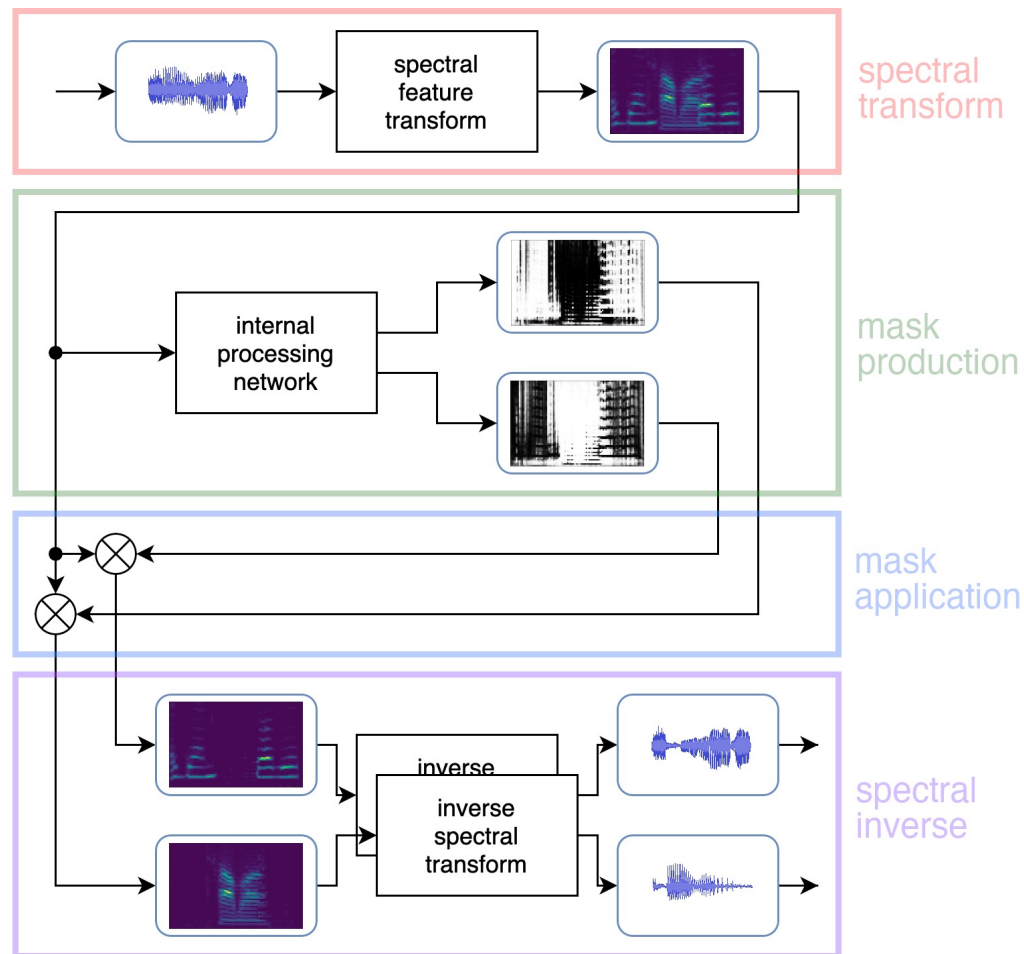
- Speech separation aims to estimate single-speaker waveforms from overlapping speech



- Relies on the spectral sparsity of speech



Separation Pipeline



Challenges in Training

Foundational approaches on mask-based loss:

- Deep Clustering (DPCL)
 - Extract embedding for each STFT bin
 - Ensure self-similarity of dominant bins from a speaker
- Permutation-Invariant Training (PIT)
 - Compute minimum loss across all output permutations, backpropagate from best permutation
- State-of-Art systems dominated by learned spectral transforms with SI-SDR PIT loss

Target Speaker Extraction

- Given a recording and an enrollment utterance or speaker representation, produce the clean speech of the enrolled speaker
- Has elements of both speech separation and speech enhancements

Multichannel Enhancement

- Collecting audio simultaneously with multiple microphones gives more information for the underlying signals
- Particularly: multiple sensors allows for localization, and multiple sources generally have different locations

Formulation

$$\begin{array}{c}
 \mathbf{x}(t) = \sum_{j=1}^J \mathbf{c}_j(t) \quad \begin{array}{l} \nearrow \text{diffuse source} \\ \searrow \text{point source} \end{array} \quad \begin{array}{l} \text{just } \mathbf{c}_j(t) \\ \text{(time-invariant)} \\ \text{spatialization} \end{array} \\
 \mathbf{x} \in \mathbb{R}^{I \times T} \quad \mathbf{c} \in \mathbb{R}^{I \times T} \quad \mathbf{c}_j(t) = \mathbf{a}_j(t) * s_j(t) \\
 I \text{ microphones} \quad \text{spatialized} \\
 \text{sources} \quad \mathbf{a}_j(t) = [a_{1j}(t), \dots, a_{Ij}(t)]^T \\
 \text{can be RIR, delay/attenuation}
 \end{array}$$

Can approximate in STFT domain:

$$\begin{aligned}
 \mathbf{a}_j(n, f) &\sim \mathbf{a}_j(f) \\
 \mathbf{c}_j(n, f) &= \mathbf{a}_j(f) s_j(n, f) \\
 \mathbf{x}(n, f) &= \mathbf{A}(f) \mathbf{s}(n, f)
 \end{aligned}$$

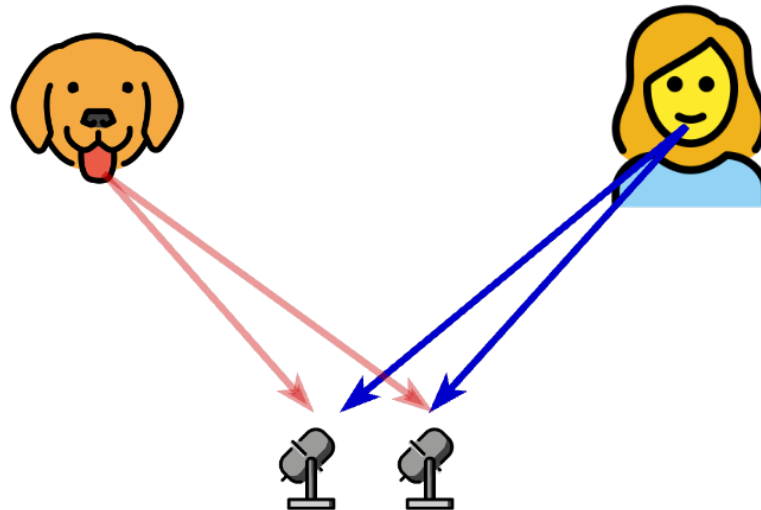
“steering vector”:

$$\mathbf{a}_j(f) \rightarrow \mathbf{d}_j(f)$$

$$\mathbf{d}_j(f) = \begin{bmatrix} \frac{1}{\sqrt{4\pi r_{1j}}} e^{-2j\pi r_{1j} v_f / c} \\ \vdots \\ \frac{1}{\sqrt{4\pi r_{Ij}}} e^{-2j\pi r_{Ij} v_f / c} \end{bmatrix} \approx \begin{bmatrix} e^{-2j\pi r_{1j} v_f / c} \\ \vdots \\ e^{-2j\pi r_{Ij} v_f / c} \end{bmatrix}$$

Beamforming

- “Delay and sum” beamforming aligns target signal temporally and misaligns other signals for constructive/destructive interference



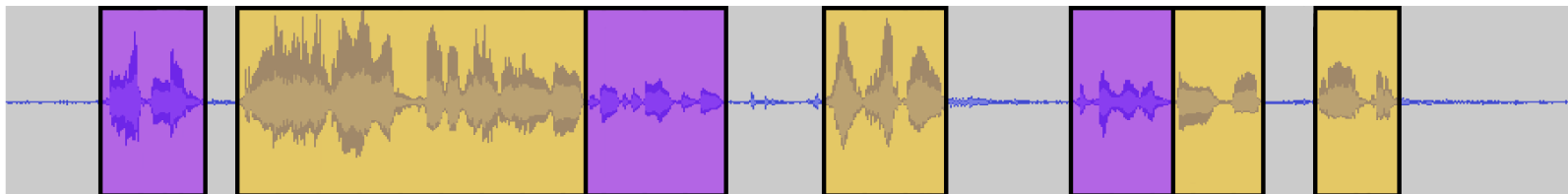
TDOA Estimation

- Beamforming requires the “time difference of arrival” (TDOA)
- Generalized Cross-Correlation with Phase Transform (GCC-PHAT)¹
- Minimum Variance Distortionless Response (MVDR) beamformer is computed in STFT domain by minimizing the power of the interfering signal
 - Weights can be computed from speech TF mask
 - Amenable to neural estimation

...questions?

(Speaker) Diarization

What is speaker diarization?



Who spoke when?

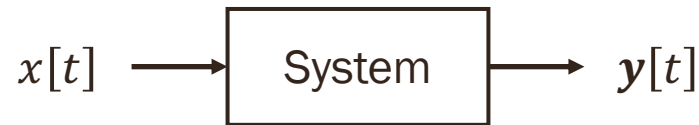
*other types of diarization exist, most notably language diarization

Why do we care?

- Many speech systems “malfunction” in multi-talker scenarios
 - Closed captioning or meeting transcription
 - Target speaker recognition
- Conversational analysis
 - Biomarkers for emotional state
 - Study of child language acquisition
 - Social role (e.g. interruptions)

Mathematical Formulation

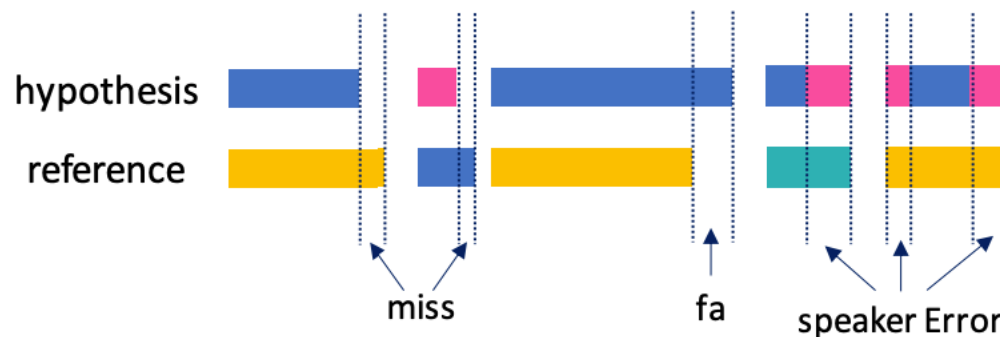
- “label-free” time series multi-label classification



$$\mathbf{y} \in \{0, 1\}^{T \times S}$$

Order of speakers $s_i \in S$ does not matter

Metrics



- Diarization Error Rate (DER%)

$$\text{DER} = \frac{\text{false_alarm} + \text{missed_speech} + \text{speaker_error}}{\text{total_speech}}$$

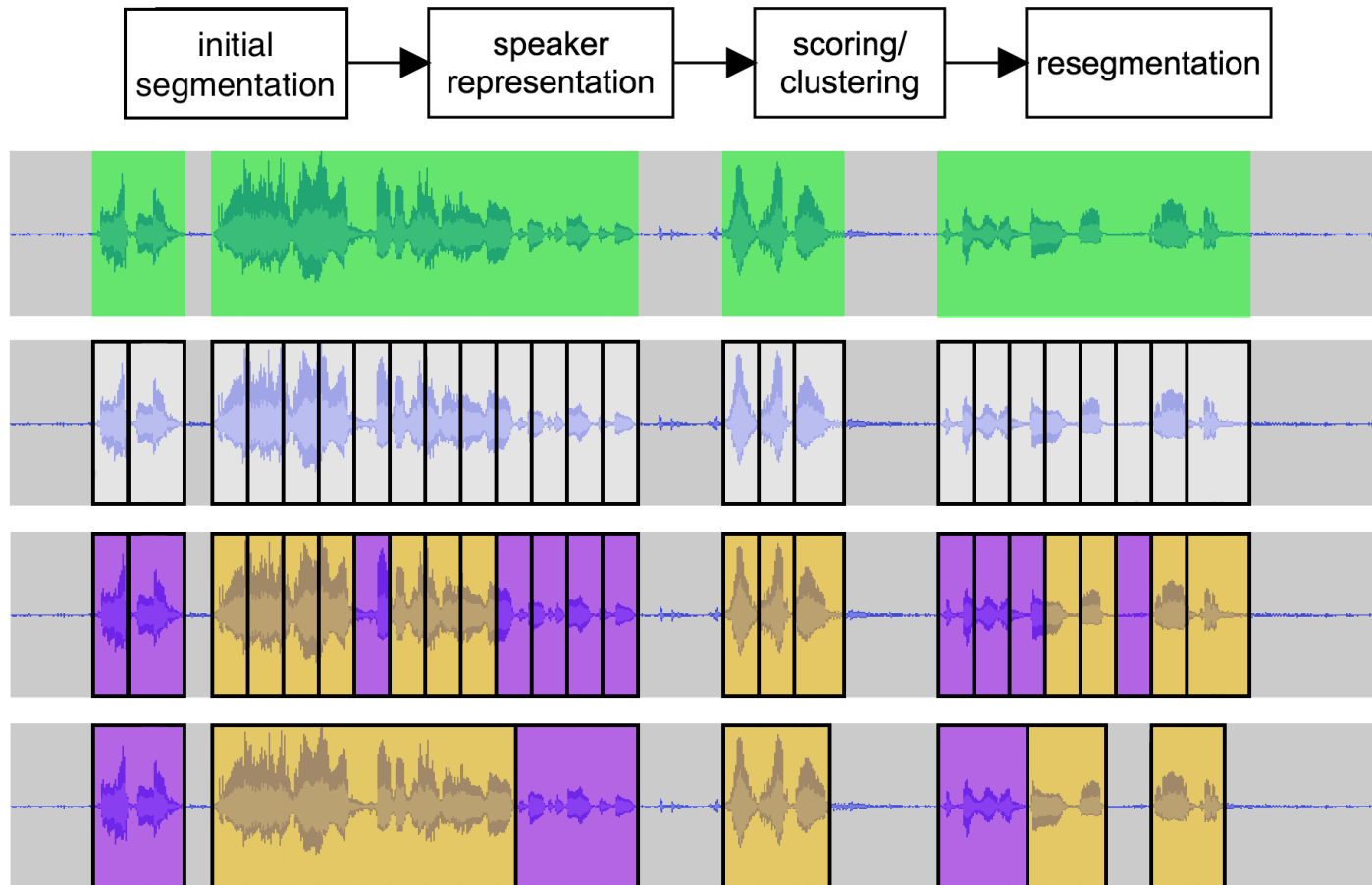
- Jaccard Error Rate (JER%)

$$\text{JER} = \frac{1}{S} \sum_{i=1}^S \frac{\text{false_alarm}_i + \text{missed_speech}_i}{\text{speech}_i}$$

Approaches to Diarization

- **Traditional “Clustering” Approaches**
 - Multi-stage pipelines with independent components
 - Individually tuned
 - Less conducive to overlap detection
- **Neural (End-to-End) Approaches**
 - Trained to produce outputs directly
 - Can be jointly optimized
 - Data hungry

Traditional Approach



Initial Segmentation

- Speech Activity Detection (SAD)
 - Basic speech presence classifier
 - Generally neural, statistical has been used
- Less commonly can be more sophisticated
 - Speaker change detection
 - Overlap detection

Speaker Representation

- Out-of-the-box Speaker ID systems
 - i-vectors, x-vectors, d-vectors
- Typically extracted under a sliding window
- Scoring can be tuned to test conditions or smaller speaker variability

Clustering

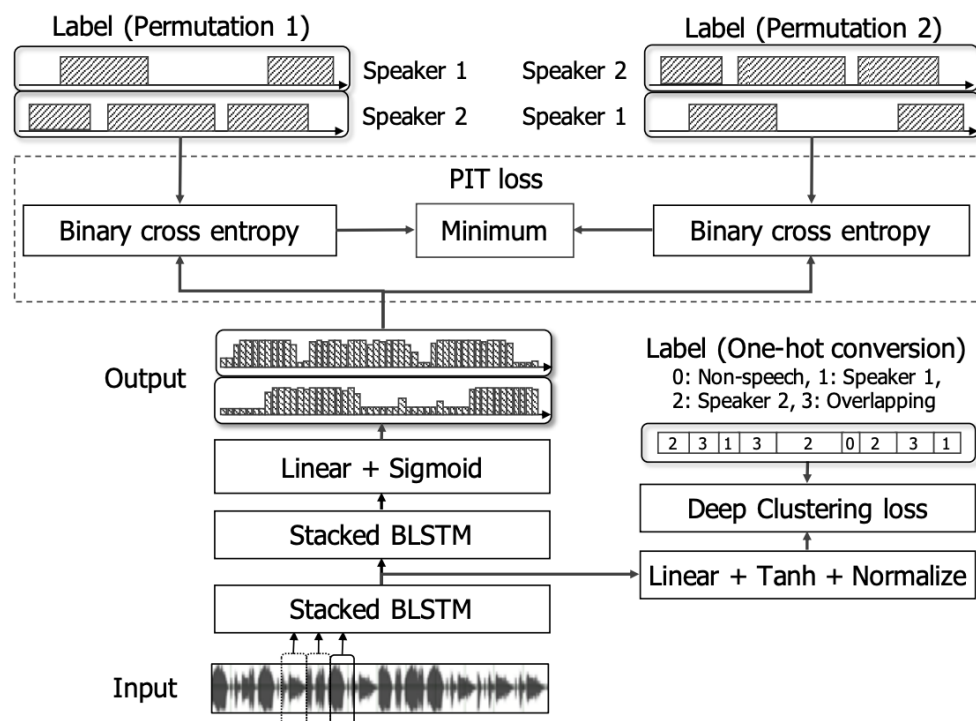
- Many clustering approaches
 - Agglomerative clustering
 - Spectral clustering
- Major challenge is speaker counting
 - Oracle (not necessarily optimal!)
 - Speaker counting
 - Thresholding/Calibration

Resegmentation

- Variational Bayes HMM of x-vectors (VBx)
 - Probabilistic model treating x-vectors as observation of latent states corresponding to speakers
 - Models the temporal aspect of conversations
- Target Speaker Voice Activity Detection (TS-VAD)
 - Speaker-specific speech activity classifier based on input speaker representation
 - Handles overlap!

Neural Diarization

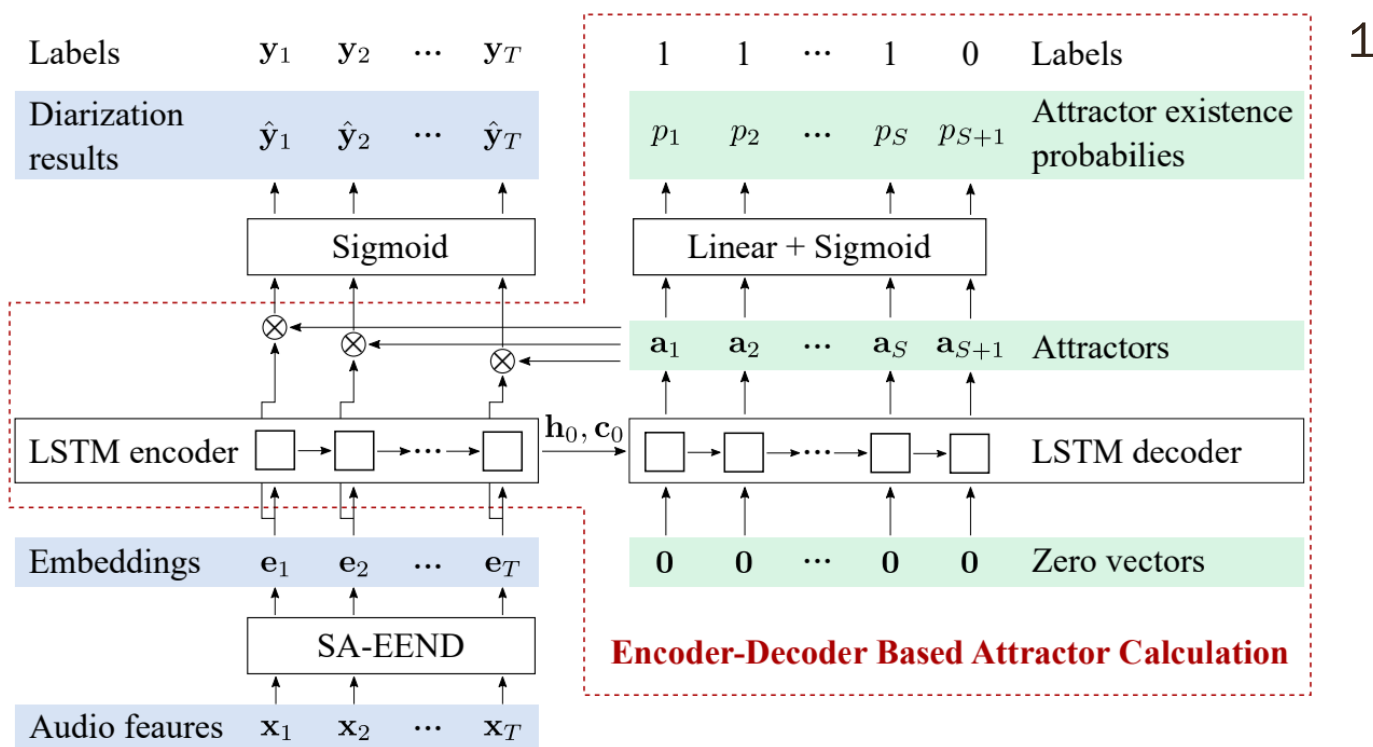
- Most methods derived from End-to-End Neural Diarization (EEND)¹ approach



1

Extension to Arbitrary Speakers

- Encoder-Decoder Attractors (EEND-EDA)¹ are used to model a variable number of speakers

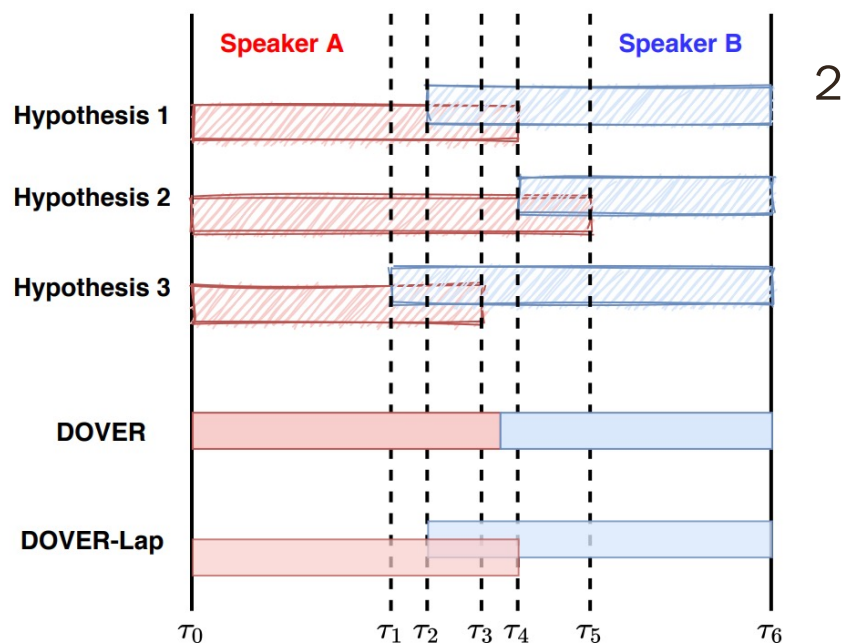


Practical Considerations

- Large amounts of data are required
- Memory requirements in training
 - Someone may talk long periods apart
- Processing long recordings
 - Must track speakers across block processing

System Ensembling

- Different systems may have different strengths and weaknesses (e.g. traditional vs. neural)
- DOVER¹ and overlap-aware extension DOVER-Lap²



Multichannel Diarization

- Multiple microphones improve localization, and different talkers will be in different locations
 - They may, however, move around
- Directional information from beamforming may be integrated into the system
- Multiple audio signals may be used directly in the system, integrating beamforming implicitly

Multimodal Diarization

- Video may contain useful information for diarization and we would like to use it
- Audio-visual diarization has been successfully done using lip region of interest features¹
 - Occlusions and out-of-frame issues pose a challenge

...questions?